



Jet Propulsion Laboratory  
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# Mars Exploration: Mission Outlook and Technology Needs

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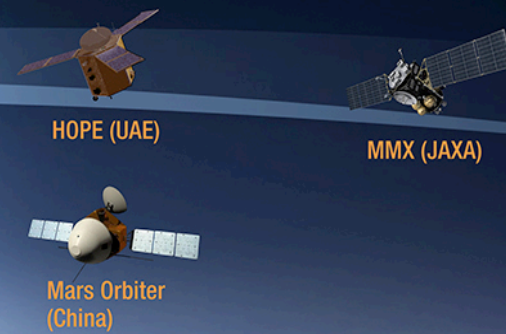
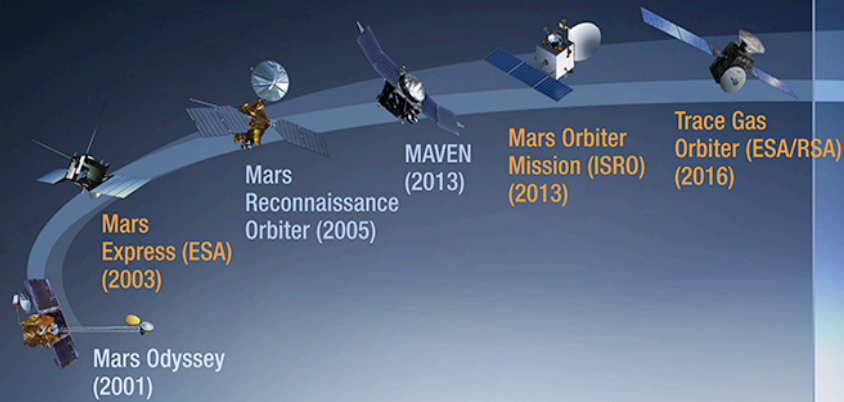




# MARS MISSIONS

OPERATIONAL 2001–2017

FUTURE 2018–2030



Opportunity  
Rover (2003)

Curiosity  
Rover (2011)

Mars Lander  
& Rover (China)

InSight

Mars 2020  
Rover (NASA)

ExoMars  
Rover (ESA/RSA)

Mars Sample  
Return (China)

Follow the Water

Explore Habitability

Seek Signs of Life

Prepare for Future Human Explorers

Planning  
NASA  
MSR



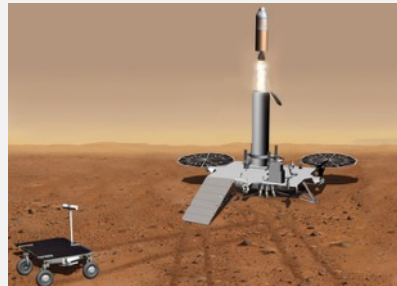
# Notional Mars Sample Return Architecture

- NASA and ESA are studying a partnership to return samples collected and cached by the Mars 2020 mission
  - NASA would lead a Sample Retrieval Lander mission
  - ESA would lead an Earth Return Orbiter mission
  - Potential launch date as early as 2026, with samples at Earth by 2031



**Sample Caching Rover  
(Mars 2020)**

- *Sample acquisition and caching*



**Sample Retrieval  
Lander**

- *Fetch Rover*
- *Orbiting Sample container (OS)*
- *Mars Ascent Vehicle*



**Earth Return  
Orbiter**

- *Rendezvous and On-Orbit Capture System*
- *Earth Entry Vehicle*



**Mars Returned Sample  
Handling**

- *Sample Receiving Facility*
- *Curation*
- *Sample science investigations*

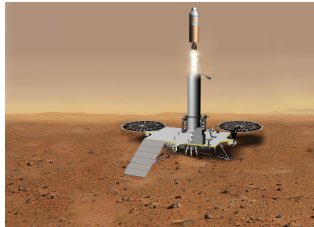
***Flight Elements***

***Ground Element***

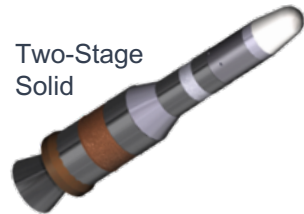


# Mars Technology Needs: Mars Sample Return

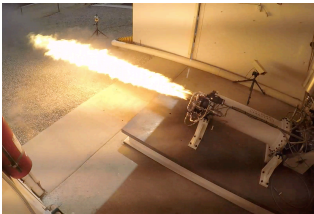
## Mars Ascent Vehicle Concept



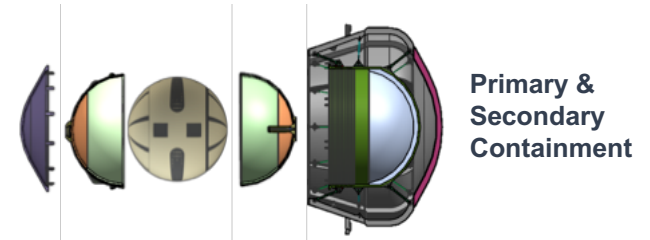
Two-Stage  
Solid



Single-Stage  
Hybrid



## Containment Assurance



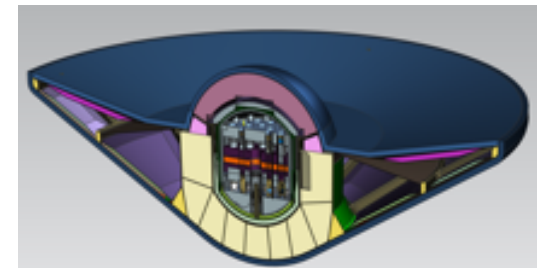
Brazing Test Articles

## Sample Fetch Rover

120 kg  
200 m/sol



## Earth Entry Vehicle



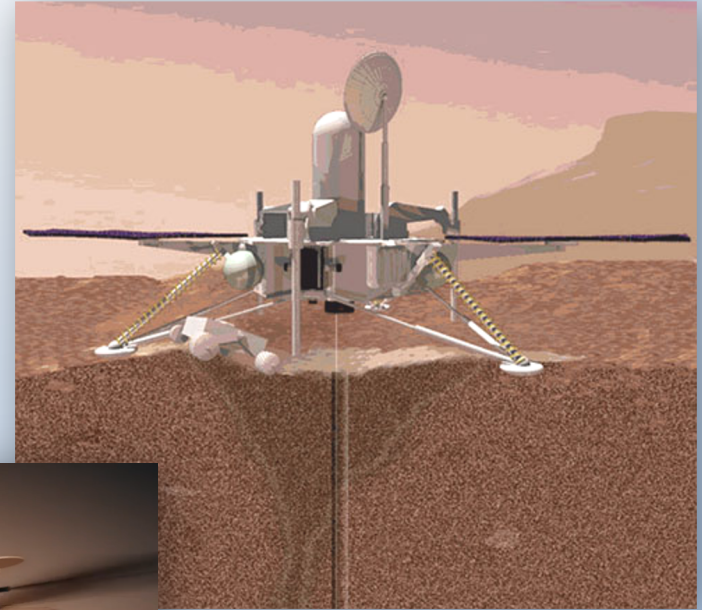


# Mars Technology Needs: New Ways of Accessing Mars

Tethered Rovers



Deep Drilling

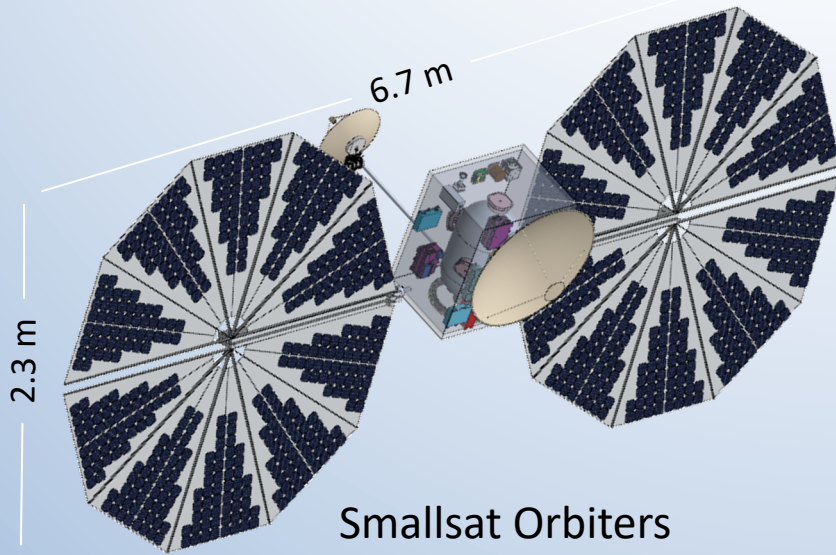


Mars Helicopters





# Mars Technology Needs: Low-Cost Mission Concepts

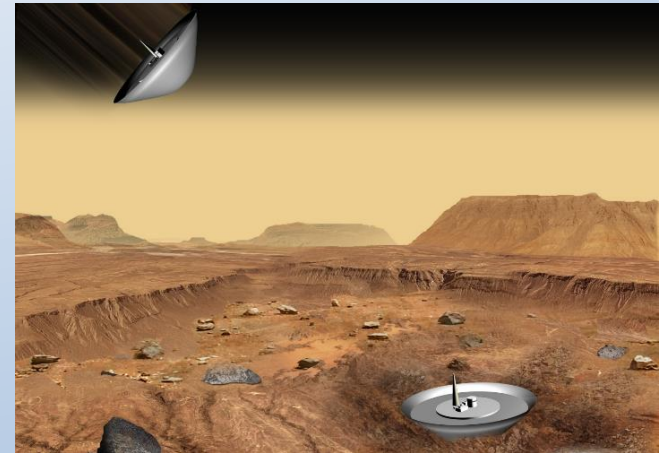


Smallsat Orbiters

~200 kg

SEP Propulsion

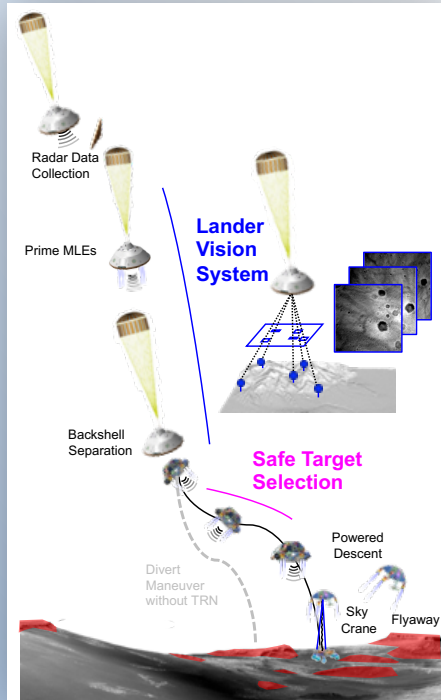
Low-cost LVs or GTO Rideshare



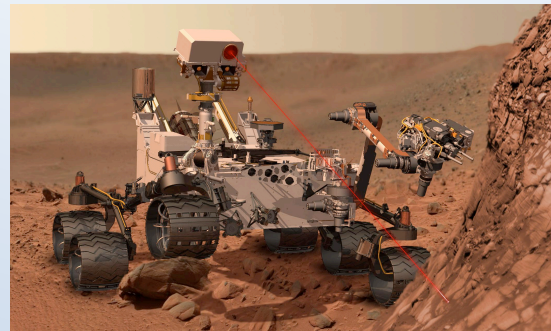
Low-complexity/Low-cost  
Hard Landers



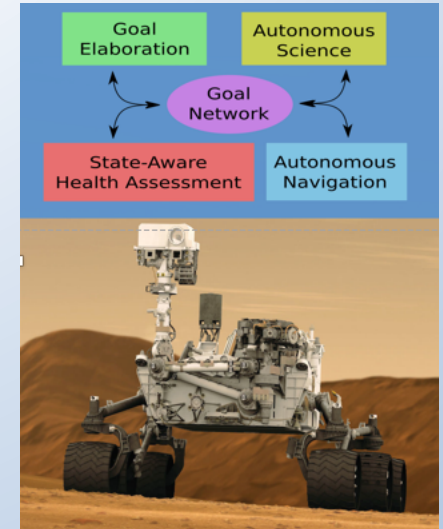
# Mars Technology Needs: Increasing Autonomy



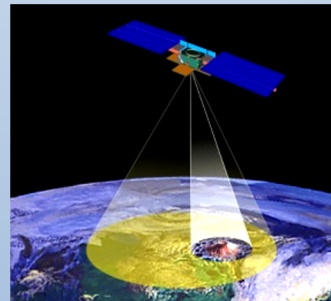
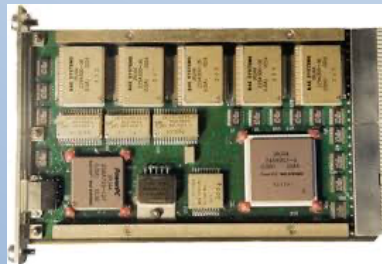
Terrain-Relative Navigation for EDL



Autonomous Science Target Selection



Self-Reliant Rovers



Onboard Analytics w/ High Performance Spaceflight Computing

# Summary

- Continuous robotic presence at Mars since 1997
- Rich mix of orbital and landed missions
- Science-driven, technology-enabled program
- Current focus on sample return planning
- Interest in accessing new regions (extreme terrains, subsurface)
- Exploring opportunities for low-cost, focused science mission concepts

***We welcome opportunities to partner with innovators in the commercial sector to identify emerging technologies that can enable new ways to explore Mars***